# A data-driven algorithm to optimize the placement of continuous monitoring sensors on oil and gas sites

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## Outline

Problem Setup





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**Experiments & Results** 



**Conclusions & Future Work** 

## Outline

Problem Setup



Algorithm

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**Experiments & Results** 



**Conclusions & Future Work** 

## **Problem Setup**

• We propose a data-driven algorithm to optimize sensor placement for continuous monitoring systems (CMS).



## **Problem Setup**

- General idea
  - Use historical wind data and available emission information to simulate M many emission scenarios.
  - Prescribe N possible sensor locations.
  - Find optimal sensor placement from all feasible configurations, under the given budget k, to maximize the detection from all M emission scenarios.

## Outline

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**Conclusions & Future Work** 

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<u>.</u>	Experiments & Results

## Algorithm

- Step 1: generate emission scenarios.
- Step 2: prescribe potential sensor locations and simulate concentrations.
- Step 3: check detection status.
- Step 4: solve an optimization problem to find the best sensor placement.



Methane Emissions Technology Evaluation Center (METEC), Colorado State University

# Algorithm

• Step 1: generate emission scenarios

#### A combination of

- wind speed time series
- wind direction time series
- emission source location
- emission rate

defines an emission scenario.



Random sample segments from historical wind time series

- Estimate a joint distribution of emission location and rate from prior knowledge
- 2. Random sample

## Step 1.1 Wind Data





## **Step 1.2 Emission Information**

		10 kg/h	20 kg/h	50  kg/h
	W.W	1/15	1/15	1/15
West Wellhead	W.S	1/15	1/15	1/15
West Separator	Т	1/15	1/15	1/15
	E.S	1/15	1/15	1/15
East Wellhead	E.W	1/15	1/15	1/15

Potential emission sources on METEC

Probability of emission location and rate pair

## Algorithm

- Step 2: prescribe possible sensor locations and simulate concentrations
  - Set possible sensor locations by gridding the site in 3D.
  - Filter out invalid locations.
  - For each (emission scenario, sensor location) pair, run Gaussian puff model to compute the CH4 concentration time series.



## Step 2.1 Sensor locations



Resolution in Easting and Northing directions = 1 m Resolution in vertical direction = 0.5 m

#### Step 2.2 Gaussian puff simulation



## Algorithm

- Step 3: check detection status
  - Use thresholds to determine if a sensor detects an emission scenario.
  - Create a detection matrix.



## Step 3.1 Thresholds

- Detection = {elevated concentration above A
  [ppm] for more than B% of time steps within the period}
- *A* is determined by sensor sensitivity
- *B* is set based on the tolerance for false positives



An example of a successful detection. A = 0.5 [ppm] B = 20%20 out of 60 (33%) points  $\ge 0.5$  [ppm].

## **Step 3.2 Detection Matrix**

Rows of D: Sensor Locations (SL)

Cols of D: Emission Scenarios (ES)

 $D_{ij} = 0$ , if SL<sub>i</sub> can detect ES<sub>j</sub>;  $D_{ij} = 1$ , otherwise

	$ES_1$	ES <sub>2</sub>	•••	$ES_j$	•••	$ES_M$
$SL_1$ -	1	1	1	0	0	1
$SL_2$ -	1	0	1	0	1	1
SL <sub>i</sub> -	0	0	0	1	1	1
:-	0	0	0	1	0	0
$SL_N$ -	1	1	0	1	0	1

Detection Matrix D

## Algorithm

- Step 4: solve an optimization problem to find the best sensor combination
  - Formulate the problem as a best subset selection task.
  - Employ the Pareto optimization framework with evolutionary algorithms (EA) to find the optimal solution.



## **Step 4.1 Best Subset Selection**



## Step 4.2 Pareto Optimization & EA

#### **Pareto Optimization**

**Objectives**:

Find a subset of rows (a solution) from the detection matrix to

- maximize emission scenario coverage.
- minimize the size of the subset.

Exhaustive search and standard linear programming algorithms are impossible for large-scale problem!

#### **Evolutionary Algorithms**

Process:

- 1. Randomly initialize a population of solutions.
- 2. Propose new solutions by perturbing existing solutions.
- 3. Update the population by eliminating worse solutions.
- 4. Repeat Step 2 & 3 until converge.
- 5. Return the best k-size solution.

## Outline

**?** Problem Setup



Algorithm



**Experiments & Results** 



**Conclusions & Future Work** 

## **Experiments & Results**

#### • Emission Scenarios

- 4-month wind data
- 5 potential source locations
- 3 possible emission rates: {10, 20, 50} [kg/h]
- $\Rightarrow$  38,130 emission scenarios

#### Sensor locations

- 1 [m] resolution in easting & northing
- 0.5 [m] resolution in vertical
- $\Rightarrow$  96,840 sensor locations



#### Experiments & Results – best-8 sensor placement



### Experiments & Results – best-k sensor placement





#### Experiments & Results – budget vs. coverage



## Outline

**?** Problem Setup



Algorithm

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**Experiments & Results** 



Conclusions & Future Work

## **Conclusions & Future Work**

- Developed a data-driven algorithm for sensor placement more accurate and efficient than traditional methods.
- The algorithm's modularity ensures adaptability to various monitoring needs.
- Optimized for solving large-scale problems efficiently.
- To implement a generative model for better approximation of wind distributions, thereby expanding the emission scenario database.
- To investigate advanced data embedding techniques to manage and solve problems of greater scale.



- Klise, Katherine A., et al. "Sensor placement optimization software applied to site-scale methane-emissions monitoring." *Journal of Environmental Engineering* 146.7 (2020): 04020054.
- Qian, Chao, Chao Bian, and Chao Feng. "Subset selection by pareto optimization with recombination." *Proceedings of the AAAI Conference on Artificial Intelligence*. Vol. 34. No. 03. 2020.

# Questions?

# Thank you for attending!

# Back up

# Background

- Methane, CH4, is the second biggest cause of climate change after CO2.
- Oil & gas sector gives off 15-20% of total methane.
- Characters of emission from oil & gas
  - high temporal variability
  - infrequent, short-lived super emitters
- Continuous monitoring system (CMS) is necessary



## Fence Line Placement on METEC



Continuous monitoring (CM) sensor

## Test EA on synthetic large matrix

- nrows = ncols = 100,000
- k = 10, randomly placement in the big matrix
- Test on 30 cases and run 10 EA algorithm for each case



## **Optimality Guarantee**

• In theory, we prove that for subset selection with monotone objective functions, PORSS can achieve the optimal polynomial-time approximation guarantee,  $1 - e^{\gamma}$  where  $\gamma$  is the submodularity ratio measuring how close your objective function is to submodularity.

## **Related Work**

	Klise et al. (2020)	Our work
# emission scenarios	1,200	≈ 40,000
<b># possible sensor locations</b>	≈ 2,500	≈ 100,000
Forward model	Gaussian plume	Gaussian puff
Optimization algorithm	Mixed-integer linear programming	Pareto optimization using evolutionary algorithm (EA)

#### EA vs. Greedy Search

• EA vs. greedy search



#### Experiments & Results - robustness

Use a different set of 10,000 emission scenarios to validate the performance of the optimal sensor placement.



## Why some scenarios are always undetected?





## **Best-1 Sensor Placement**

Best-1 sensor placement, coverage ratio = 0.40





### **Best-2 Sensor Placement**

Best-2 sensor placement, coverage ratio = 0.65





#### **Best-3 Sensor Placement**

Best-3 sensor placement, coverage ratio = 0.75





#### **Best-4 Sensor Placement**

Best-4 sensor placement, coverage ratio = 0.82





### **Best-5 Sensor Placement**

Best-5 sensor placement, coverage ratio = 0.86





#### **Best-6 Sensor Placement**

Best-6 sensor placement, coverage ratio = 0.89





#### **Best-7 Sensor Placement**

Best-7 sensor placement, coverage ratio = 0.92





#### **Best-8 Sensor Placement**

Best-8 sensor placement, coverage ratio = 0.93





#### **Best-9 Sensor Placement**

Best-9 sensor placement, coverage ratio = 0.95



#### **Best-10 Sensor Placement**

Best-10 sensor placement, coverage ratio = 0.96

